



Problems
Main Results
Proofs
Some Discussions

On time regularity of generalized Ornstein-Uhlenbeck processes with cylindrical stable noise

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1 Problems

$$dX(t) = AX(t)dt + dL(t), t \geq 0. \quad (1)$$

H , a separable Hilbert space, $\langle \cdot, \cdot \rangle_H$.

A , generator of a C_0 -semigroup on H , A^* the adjoint operator of A .

L , Lévy process, $L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$,

L^n i.i.d., càdlàg real-valued Lévy processes.

$\{e_n\}_{n \in \mathbb{N}}$ fixed reference orthonormal basis in H .

β_n a sequence of positive numbers.

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Problem :

If the solution of Eq. (1) $(X(t))_{t \geq 0}$ takes value in H for any t , is there a H -valued càdlàg modification of X ? i.e. $\exists ?$ a H -valued càdlàg $(\tilde{X}_t)_{t \geq 0}$ such that,

$$\mathbb{P}(X_t = \tilde{X}_t) = 1, \text{ for any } t. \quad (2)$$

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Assume that $\{e_n\}_{n \in \mathbb{N}} \subset \mathcal{D}(A^*)$, the weak solution of Eq. (1),

$$dX(t) = AX(t)dt + dL(t), \quad t \geq 0.$$

can be represented by for any $n \in \mathbb{N}$,

$$d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t). \quad (3)$$

$$\langle X(t), e_n \rangle_H \equiv X^n(t).$$

L^n , α -stable processes, $\alpha \in (0, 2)$.

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1.1. Property of Sample Paths

Kolmogorov's Extension Theorem:

\mathcal{S} : State space.

construct distribution on $\mathcal{S}^{[0, \infty)}$.

However, this theorem does not describe the properties of sample paths.

Continuous or càdlàg modification of sample path is a fundamental property in Theory of Stochastic Processes, such as Martingale Theory, Markov Processes and Probabilistic Potential Theory and SDE.

[1] Doob, J.L. *Stochastic Processes*. John Wiley & Sons Inc., New York 1953

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1.2. Generalized Ornstein-Uhlenbeck Processes

$$dX(t) = AX(t)dt + dL(t).$$

$L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$, L^n i.i.d., càdlàg α -stable processes.

Modeling some heavy tail phenomenon.

The time regularity of the process X is of prime interest in the study of non-linear Stochastic PDEs.

And these studies of generalized O-U processes is a beginning point .

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1.3. l^2 -valued O-U processes driven by Brownian motion

- l^2 -valued O-U processes driven by Brownian motion

[2] Iscoe, Marcus, McDonald, Talagrand, Zinn, (1990) *Ann. Proba.*

$$dx_k(t) = -\lambda_k x_k(t)dt + \sqrt{2a_k}dB_k, \quad k = 1, 2, \dots .$$

They gave a simple but quite sharp criterion for continuity of X_t in l^2 .

Theorem 1 in [2] $f(x)$ positive function on $[0, \infty)$ such that $\frac{f(x)}{x}$ nondecreasing for $x \geq x_1 > 0$ and

$$\int_{x_1}^{\infty} \frac{dx}{f(x)} < \infty, \quad \sum_k \frac{a_k}{\lambda_k} < \infty, \quad \sup_k \frac{f(a_k) \vee x_1}{\lambda_k \vee 1} < \infty. \quad (4)$$

Then, x_t is continuous in l^2 a.s. Moreover, this result is best possible in the sense that it is false for any function $f(x)$, which satisfies all the above hypotheses with the exception that $\int_{x_1}^{\infty} \frac{dx}{f(x)} = \infty$.

- H or B -valued O-U processes

[3] Millet, Smolenski (1992) *Prob. Theory Related Fields.*

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1.3.1. O-U Eq. with Lévy noise

[4] Fuhrman, Röckner (2000) *Generalized Mahler semigroups: the non Gaussian case*, Potential Anal., 12(2000), 1-47.

- *There is an enlarged space E , $H \subset_{\text{HS}} E$, such that $(X(t))_{t \geq 0}$ has a càdlàg path in E .*

[5] Priola, E., Zabczyk, J. *On linear evolution with cylindrical Lévy noise*, in: SPDE and Applications VIII, Proceedings of the Levico 2008 Conference.

- *$L(t)$ symmetric, and $L(t) \in U \supset H$, they give a necessary and sufficient condition of $X_t \in H$, for any $t > 0$.*

[6] Brzeźniak, Z., Zabczyk, J. *Regularity of Ornstein-Uhlenbeck processes driven by Lévy white noise*, Potential Anal. 32(2010)153-188.

- *$L(t)$, Lévy white noise obtained by subordination of a Gaussian white noise. $L_t = W(Z(t))$, Spatial continuity, Time irregularity.*

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[7] Priola, E., Zabczyk, J. *Structural properties of semilinear SPDEs driven by cylindrical stable process*, Probab. Theory Related Fields, 149(2011), 97-137 [PZ11]

- They conjectured in Section 4 in [7], If L^n are symmetric α -stable processes, $\alpha \in (0, 2)$, the H -càdlàg property of Eq. (1) holds **under much weaker conditions than** $\sum_{n=1}^{\infty} \beta_n^\alpha < \infty$.

Remark 1. $\sum_{n=1}^{\infty} \beta_n^\alpha < \infty \Leftrightarrow L(t) = \sum_{n=0}^{\infty} \beta_n L^n(t) e_n$ has H -càdlàg property.

Remark 2. In general, $L \in H \Rightarrow X$ has H -càdlàg path.

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[8] Brzeźniak, Z., Goldys, B., Imkeller, P., Peszat, S., Priola, E., Zabczyk, J. *Time irregularity of generalized Ornstein-Uhlenbeck processes*, C. R. Acad. Sci. Paris, Ser. I 348(2010), 273-276. [BGIPPZ10]

$$dX(t) = AX(t)dt + dL(t), t \geq 0.$$

$$d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t), n \in \mathbb{N}. \quad (5)$$

$$\langle X(t), e_n \rangle_H \equiv X^n(t).$$

• **Theorem 2.1 [8]** X , H -valued process $(e_n) \in \mathcal{D}(A^*)$, $\beta_n \rightarrow 0$, then X has no H -càdlàg modification with probability 1.

• Question 1,2,3,4

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[9] Brzeźniak, Z., Otobe, Y. and Xie B. *Regularity for SPDE driven by α -stable cylindrical noise. 2011, preprint*

- They obtained detailed results of spatial regularity and temporal integrability.

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2 Main Results

$L = \sum_{n=1}^{\infty} \beta_n L^n(t) e_n$, L^n i.i.d. real-valued Lévy processes, Lévy characteristic measure ν . $\{e_n\}_{n \in \mathbb{N}} \subset \mathcal{D}(A^*)$,

$$d\langle X(t), e_n \rangle_H = \langle X(t), A^* e_n \rangle_H dt + \beta_n dL^n(t).$$

Theorem 1 Assume that the process X in Eq. (1) has H -càdlàg modification, then for any $\epsilon > 0$, $\sum_{n=1}^{\infty} \nu(|y| \geq \epsilon/\beta_n) < \infty$.

Remark 3. This theorem implies Theorem 2.1 in [BGIPPZ10]

$\beta_n \rightarrow 0 \Rightarrow$ no H -càdlàg modification

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L^n , i.i.d. α -stable process. $\nu(dy) = \begin{cases} c_1 y^{-1-\alpha} dy, & y > 0, \\ c_2 |y|^{-1-\alpha} dy, & y < 0. \end{cases}$

Theorem 2 Assume $(L^n, n = 1, 2, \dots)$ are i.i.d., non-trivial α -stable processes, $\alpha \in (0, 2)$, and $S(t) = e^{At}$ satisfying $\|S(t)\|_{L(H,H)} \leq e^{\beta t}$, $\beta \geq 0$, (generalized contraction principle), the following three assertions are equivalent:

- (1) the process $(X(t), t \geq 0)$ in Eq. (1) has H -càdlàg modification;
- (2) $\sum_{n=1}^{\infty} |\beta_n|^\alpha < \infty$;
- (3) the process L is a Lévy process on H .

Remark 4. This result denies the conjecture in [PZ11]. And more, Theorem 2 does not need the assumption of symmetry of L_n .

much weaker than $\sum_{n=1}^{\infty} |\beta_n|^\alpha < \infty$.



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Remark 5. In [BGIPPZ10],

Question 3: *Is the requirement of the process L evolves in H also necessary for the existence of H -càdlàg modification of X ?*

Theorem 2 partly answers Question 3, *i.e.* at least if L^n , i.i.d. α -stable processes, L evolving in H is a necessary condition of X having H -càdlàg modification.

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Moreover, if A is self-adjoint, eigenvectors e_n , eigenvalues $-\lambda_n < 0$, $n \in \mathbb{N}$,

$$dX^n(t) = -\lambda_n X^n(t)dt + \beta_n dL^n(t), \quad t \geq 0, \quad n \in \mathbb{N}. \quad (6)$$

For $\delta \in \mathbb{R}$,

$$H_\delta \equiv \mathcal{D}(A^{\delta/2}) = \left\{ x = \sum_{n=1}^{\infty} x_n e_n : \sum_{n=1}^{\infty} \lambda_n^\delta |x_n|^2 < \infty, x_n \in \mathbb{R} \right\}.$$

Proposition 3 Assume L^n are i.i.d., non-trivial α -stable processes, $\alpha \in (0, 2)$ and X^n is the solution of Eq. (6). Then the following assertions are equivalent:

- (1) the process $(X(t), t \geq 0)$ in Eq. (1) has H_δ -càdlàg modification;
- (2) $\sum_{n=1}^{\infty} |\beta_n \lambda_n^{\delta/2}|^\alpha < \infty$;
- (3) the process L is a Lévy process on H_δ .

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Furthermore, we apply Proposition 3 to Stochastic Heat Equation (S.H.E.) on $\mathcal{O} = (0, \pi)$ with α -stable noise

$$dX(t) = \Delta X(t)dt + dL(t), \quad (7)$$

Proposition 4 *If $\beta_n = 1$ for any $n \in \mathbb{N}$, Eq. (7) has H_δ -càdlàg modification if and only if $\delta < -1/\alpha$.*

Remark 6. in [BGIPPZ10]

Question 4: *Is the process X in S.H.E. H_δ -càdlàg for $\delta \in [-\frac{1}{\alpha}, 0)$?*

Proposition 4 answers Question 4.

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Proposition 5 Assume L^n are i.i.d., non-trivial symmetric α -stable processes. If $(\beta_n, n \geq 1)$ satisfies $\sum_{n=1}^{\infty} \beta_n^\alpha/n^2 < \infty$ and $\sum_{n=1}^{\infty} \beta_n^\alpha = \infty$, then there is no H -càdlàg modification of $(X(t), t \geq 0)$ in Eq. (7), even if for any $t > 0$, $X(t) \in H$.

Remark 7. In [BGIPPZ10],

Question 1: Does $\beta_n \rightarrow 0$ imply existence of a càdlàg modification of X ?

If we set $\beta_n = n^{-\frac{1}{\alpha}}$, then $\sum_{n=1}^{\infty} \beta_n^\alpha/n^2 < \infty$, $\sum_{n=1}^{\infty} \beta_n^\alpha = \infty$ and $\beta_n \rightarrow 0$ in Eq. (7) (S.H.E.). By Proposition 5, we give an example showing that $\beta_n \rightarrow 0$ does not imply the existence of H -càdlàg modification of X , even if for any $t > 0$, $X(t) \in H$ and the Lévy characteristic measure of L supports on H . This is a negative answer to Question 1 .

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Remark 8. Question 2 in [BGIPPZ10]: Is $e_n \in \mathcal{D}(A^*)$ essential for the validity of Theorem 2.1 .

We have no idea to this question.

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3 Proofs

$$X(t) = \sum_{n=1}^{\infty} X^n(t)e_n, \quad X^n(t) = \langle X(t), e_n \rangle_H$$

Lemma 1 *The process $(X(t), t \geq 0)$ is a H -càdlàg (resp. continuous) process with probability 1 if and only if for any $n \in \mathbb{N}$, the process $(X^n(t), t \geq 0)$ is càdlàg (resp. continuous) process with probability 1 and for any $T > 0$,*

$$\lim_{N \rightarrow \infty} \sup_{t \in [0, T]} \sum_{i=N}^{\infty} |X^i(t)|^2 = 0, \quad \text{with probability 1.} \quad (8)$$

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Set $\Delta f(t) = f(t) - f(t-)$. Noting that if $(X(t), t \geq 0)$ is a H -càdlàg process, then

$$\sup_{n \geq N} \sup_{t \in [0, T]} |\Delta X^n(t)| \leq 2 \left(\sup_{t \in [0, T]} \sum_{n=N}^{\infty} |X^n(t)|^2 \right)^{1/2}$$

Lemma 2 Assume the process $(X(t), t \geq 0)$ is a H -càdlàg process with probability 1, then for any $T > 0$,

$$\lim_{N \rightarrow \infty} \sup_{n \geq N} \sup_{t \in [0, T]} |\Delta X^n(t)| = 0, \text{ with probability 1.}$$

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Proof of Theorem 1 X H -càdlàg property.

$$\tau_n = \inf\{t > 0 : |\beta_n \Delta L^n(t)| \geq \epsilon\}$$

τ_n independent exponential distributions with parameter $\psi_n = \nu(|y| \geq \epsilon/\beta_n)$.

Lemma 2 implies

$$\lim_{N \rightarrow \infty} \mathbb{P}(\tau_n \leq T, \text{ for some } n \geq N) = 0.$$

$$\mathbb{P}(\tau_n \leq T, \text{ for some } n \geq N) = 1 - \prod_{n \geq N} \mathbb{P}(\tau_n \leq T) = 1 - \exp\left(-\sum_{n=N}^{\infty} \psi_n T\right)$$

$$\sum_{n=1}^{\infty} \nu(|y| \geq \epsilon/\beta_n) = \sum_{n=1}^{\infty} \psi_n < \infty.$$



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Applying Theorem 1 to α -stable processes,

$$\nu(dy) = \begin{cases} c_1 y^{-1-\alpha} dy, & y > 0, \\ c_2 |y|^{-1-\alpha} dy, & y < 0. \end{cases}$$

Theorem 2 holds.

Key point: scaling invariant law of α -stable law, or power law.

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Proof of Lemma 1:

⇐ If

$$\lim_{N \rightarrow \infty} \sup_{t \in [0, T]} \sum_{i=N}^{\infty} |X^i(t)|^2 = 0, \quad \text{with probability 1,} \quad (9)$$

then for any $t \in [0, \infty)$, for any $\epsilon > 0$, by Eq.(9), there exists $N_{t, \omega, \epsilon} \in \mathbb{N}$ satisfying $\sup_{s \in [0, t+1]} \sum_{i=N_{t, \omega, \epsilon}}^{\infty} |X^i(s)|^2 \leq \epsilon$.

$$\limsup_{s' \downarrow t} \|X(s') - X(t)\|_H^2 \quad (10)$$

$$\leq \lim_{s' \downarrow t} \sum_{i=1}^{N_{t, \omega, \epsilon}} |X^i(s') - X^i(t)|^2 + 2 \sup_{s \in [0, t+1]} \sum_{i=N_{t, \omega, \epsilon}}^{\infty} |X^i(s)|^2 \leq 2\epsilon. \quad (11)$$

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⇒ • V is a separable Hilbert space,

K is a compact set in V

⇔

K is bounded, closed and,

and for any orthonormal basis $\{v_n\}_{n \in \mathbb{N}}$ in V , for any $\epsilon > 0$, there is a $N_\epsilon \in \mathbb{N}$

$$\sup_{x \in K} \sum_{i=N_\epsilon}^{\infty} \langle x, v_i \rangle_V^2 < \epsilon.$$

• By the Proposition 1.1 in [10], for any $x \in D([0, T], H)$,

$$\{x(t), t \in [0, T]\} \cup \{x(t-), t \in [0, T]\}$$

is a compact set in H .

[10] Jakubowski, A. *On the Skorohod topology*, Ann. Inst. Henri Poincaré 22(1986), 263-285.



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4 Some Discussions

4.1. Conclusions

We give a necessary and sufficient condition of càdlàg modification of Ornstein-Uhlenbeck process with cylindrical stable noise in a Hilbert space. By using this condition, we deny a conjecture and answer some questions.

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4.2. Further problems

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$$dY(t) = AY(t)dt + F(Y(t))dt + dL(t).$$

$$dX(t) = AX(t)dt + dL(t)$$

Formally, let $z(t) = Y(t) - X(t)$,

$$\frac{dz(t)}{dt} = Az(t) + F(z(t) + X(t)).$$

This is a deterministic PDE with “random coefficients”.

If $z \in C([0, T], H)$, then Y and X have the same H -càdlàg property.

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$$dY(t) = AY(t)dt + F(Y(t), \nabla Y(t))dt + dL(t).$$
$$\frac{dz(t)}{dt} = Az(t) + F(z(t) + X(t), \nabla(z(t) + X(t))).$$

Difficult problems: Spatial-Temporal regularity and integrability of X are necessary.

These works is in progress... ...

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- $X \in B$, Banach space, ?
- Itô-Stratonovich type SPDE and interacting diffusions driven by stable processes. Time (ir)regularity ? such as Parabolic Andersen Model on \mathbb{Z}^d .

$$dX_i(t) = \kappa \sum_{j \in \mathbb{Z}^d} a(i, j) X_j(t) dt + X_i(t-) dL_i(t), \quad i \in \mathbb{Z}^d.$$

[11] Furuoya, T., Shiga, T., *Sample lyapunov exponent for a class of linear Markovian systems over \mathbb{Z}^d* . Osaka J. Math 35 (1998) 35-72

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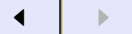
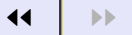
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